

An Empirical Analysis of Entropy Search in Batch Bayesian Optimisation

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Introduction

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Batch Bayesian Optimisation with Classical Methods:

- Probability of Improvement, Expected Improvement, Upper Confidence Bound
- can be applied to batch using Markov Chain Monte Carlo methods
- selection set is populated sequentially

$$\alpha_{PI-MCMC}(x|\{x_d\}_{d=1}^q) = \int_{\mathcal{X}^q} [\alpha_{PI}(x|D_n \cup \{x_d, y_d\}_{d=1}^q) (\{y_d\}_{d=1}^q | D_n, \{x_d\}_{d=1}^q) dy_1 \dots dy_q]$$

- double greedy, myopic selection

Entropy Search methods:

- non-greedy by design
- considers information-theoretic concepts: information gain, information entropy

$$\alpha_{ES}(x) = H[p(x^*|D_n)] - E_{p(y|D_n, x)}[H(p(x^*|D_n \cup \{x, y\}))] \quad (1)$$

- easily applied to batch

$$\alpha(\{x_q\}_{q=1}^Q) = \sum_{q=1}^Q \alpha(x_q|\{x'_q\}_{q=1}^q)$$

Predictive Entropy Search (PES) [1]:

- derived from equation (1)

$$\alpha_{PES}(x) = H[p(y|D_n, x)] - \mathbb{E}_{p(x^*|D_n)}[H(p(y|D_n, x, x^*))]$$

- compute the change in the entropy of the predictive distribution at the optimum's position
- analytically tractable

Max-Value Entropy Search (MES) [2]:

- considers entropy over maximum function value

$$\alpha_{MES}(x) = H[p(y|D_n, x)] - \mathbb{E}_{p(y^*|D_n)}[H(p(y|x, D_n, y^*))]$$

- marginalized over sampled maximum values
- robust and efficient implementation

Joint Entropy Search (JES) [3]:

- combines ideas from PES and JES

$$\alpha_{JES}(x) = H[p(y|D_n, x)] - \mathbb{E}_{p(x^*, y^*|D_n)}[H(p(y|D_n \cup (x^*, y^*), x, y^*))]$$

Literature gap:

- systematic study on the performance of PES, MES, JES in parallel optimisation across various environment settings
- batch sizes, function dimensions, noise levels, types of objective functions

Research question

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How do Entropy Search algorithms perform under various environment specifications, and what are the factors influencing their performance?

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Batch sizes (q): {2, 5, 10, 25}

Noise levels: {0%, 5%, 10%, 20%, 40%}

- percentage of range of values of objective function

Input dimensions (D): {2, 5, 10, 25, 50}

Function shapes:

- unimodal: Easom, Zakharov, Sum of Different Powers
- multimodal: Griewank, Ackley, Schwefel

Methodology

Fractional Factorial Design:

- used to assemble the testing configurations
- exposes information about the most important features of the studied problem
- 26 testing environments

Metrics:

- simple regret
- cumulative regret

Algorithms:

- qPES, qMES, qJES as implemented in BOTorch
- random and qEI
- results averaged over 5 runs

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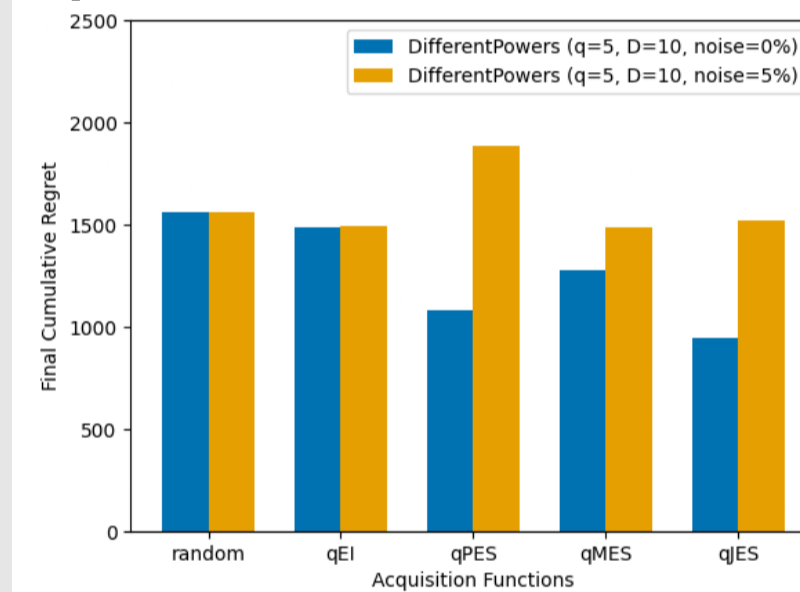


Figure 2: Performance of acquisition functions in high-dimensional unimodal function after 50 iterations

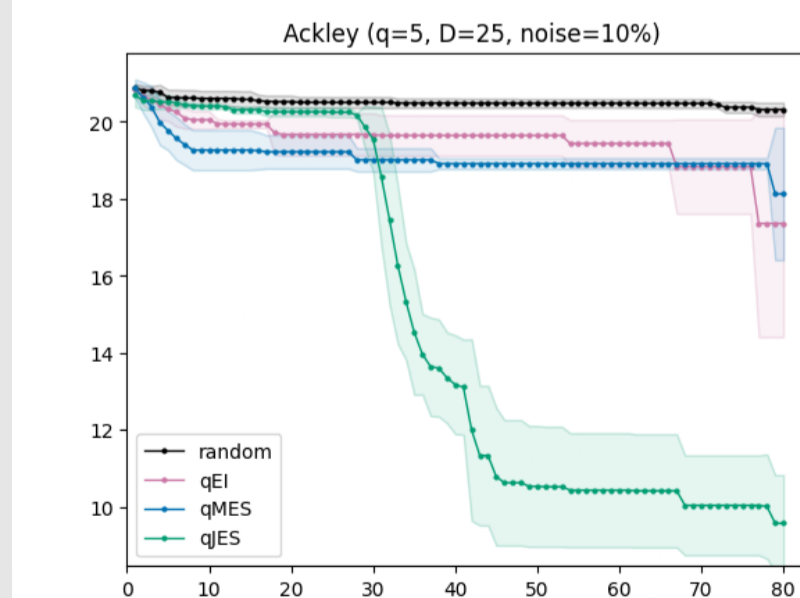


Figure 3: Ackley run

Results

ES has better performance for batch BO

Noise is the most influential parameter

- especially in high-dimensional spaces

Increased efficiency for unimodal functions with discernable slope

- optimisation failed for Easom, which has a small optimum area surrounded by a flat outer region

qJES is most robust to greater input dimensions

- qPES also looks promising pending further testing

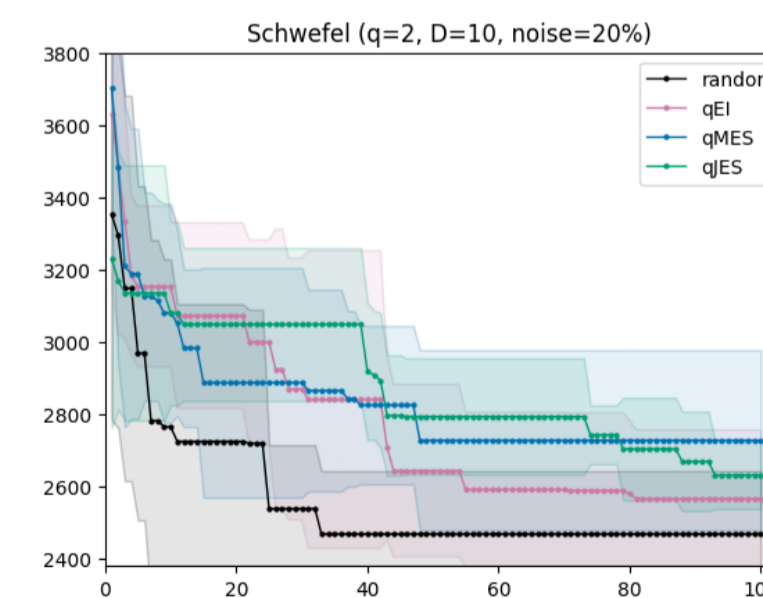


Figure 3: Schwefel run

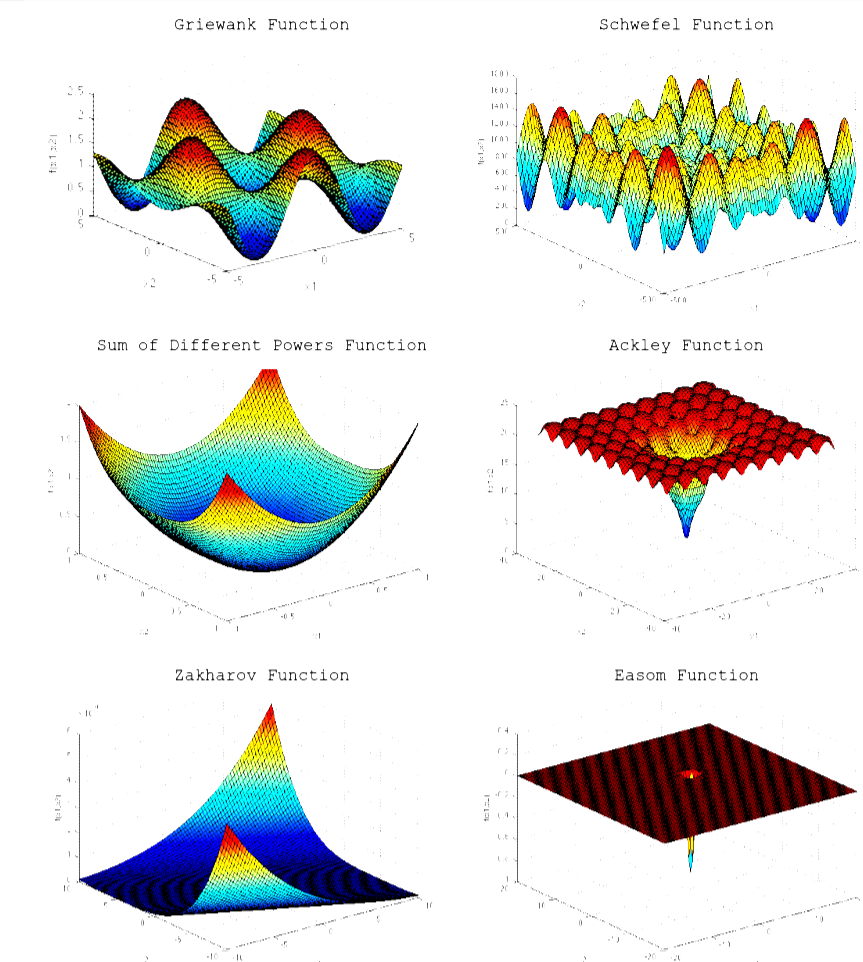


Figure 1: 2-dimensional representation of the functions used for evaluation

Function	Average runtime (s)
qEI	1.14
qPES	13.62
qMES	3.13
qJES	24.95

Table 1: Average runtime of studied algorithms. Note that qPES was run with GPU acceleration

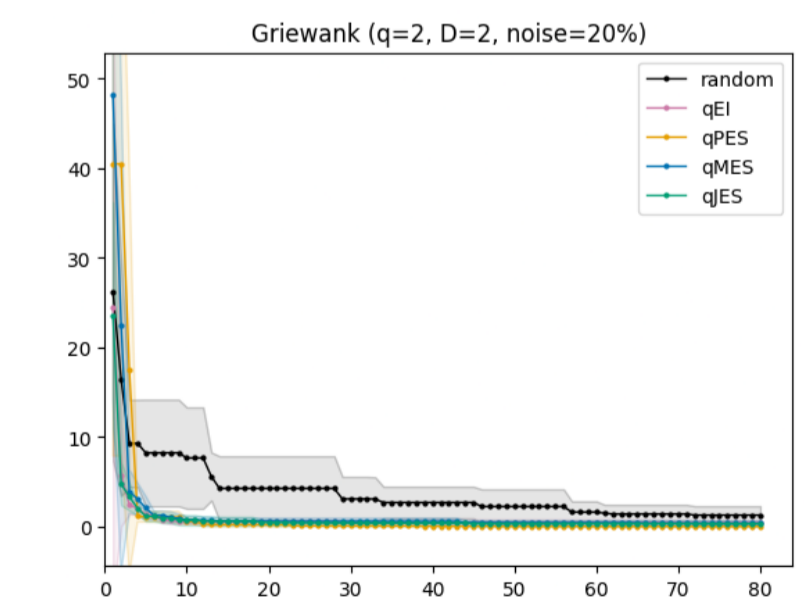


Figure 4: Griewank run

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Future work

Explore more complex scenarios:

- input-dependant noise
- misspecified environments
- multi-objective optimisation

Different metrics:

- inference regret

Real-World Benchmarking

References: [1] Jose Hernández, Matthew Hoffman, and Zoubin Ghahramani. Predictive entropy search for efficient global optimization of black-box functions. [2] Zi Wang and Stefanie Jegelka. Max-value entropy search for efficient bayesian optimization [3] Carl Hvarfner, Frank Hutter, and Luigi Nardi. Joint entropy search for maximally-informed bayesian optimization.