

Genetic Algorithms for Inductive Program Synthesis

M.R. Tromp
M.R.Tromp@student.tudelft.nl

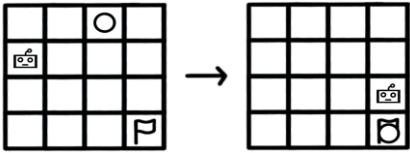
Supervisor:
S. Dumančić



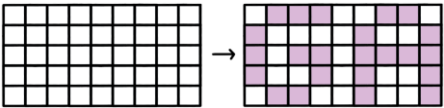
1. Background

Inductive Program Synthesis

Robot Domain



ASCII Art Domain



String Domain

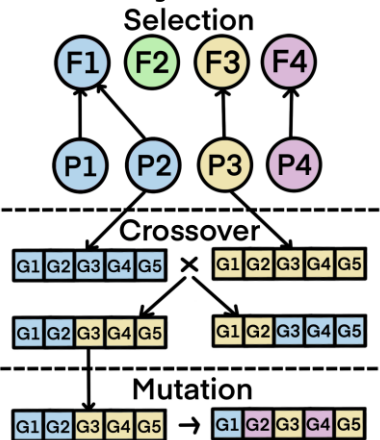
"Genetic Algorithm" → "GA"

Brute

- Best-first search
- Stuck in local optima

VanillaGP

- Genetic Algorithm



- Created to circumvent local optima
- Outperforms Brute on 1/3 domains

2. Research question

Are there **alternatives** for the **components** of VanillaGP that will allow it to solve a higher percentage of tasks within the given domains during the same time frame?

3. VanillaGP Implementations

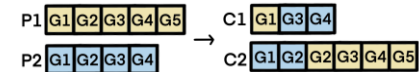
Selection:

Stochastic Universal Sampling (SUS)

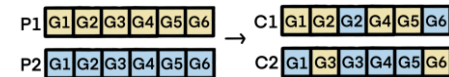


Crossover:

One-Point Crossover

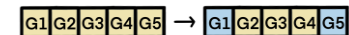


N-Point Crossover

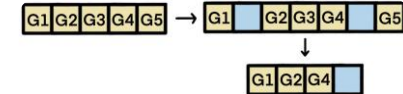


Mutation:

Classical Mutation



Uniform Mutation by Addition and Deletion



4. Selection

Roulette Wheel Selection



Lexicase

Down-Sampled Lexicase (DSLX)

Combined Lexicase

Tournament

Truncation

5. Crossover

Two-Point



Uniform



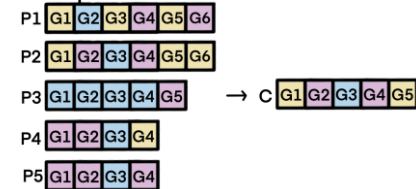
Queen Bee



Three Parent (TPC)



Multiple Parent

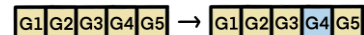


Random

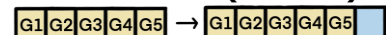


6. Mutation

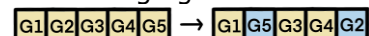
One Mutation Per Solution (OMPS)



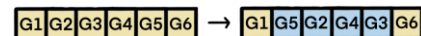
Altered OMPS (AOMPS)



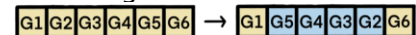
Interchanging Mutation



Scramble Mutation



Reversing Mutation

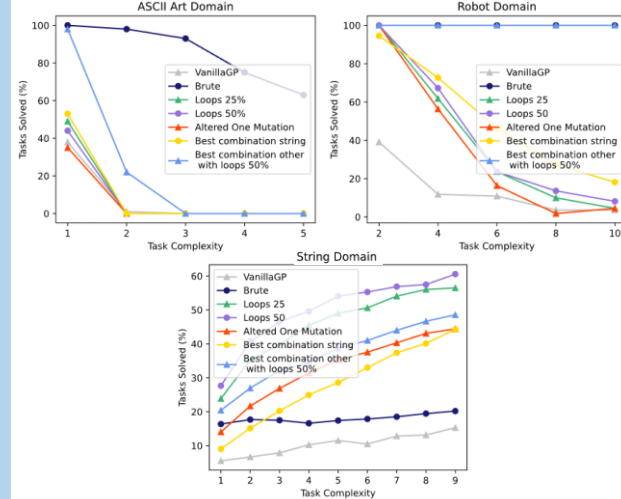


7. Combinations

Many combinations, most did not perform significantly better

- Main limitation is lack of loops in programs

One more alternative, AOMPS with more loops



- Performs much better
- DSLX, TPC, Loops AOMPS
 - Robot domain
 - ASCII Art domain
- SUS, One-Point, Loops AOMPS
 - String domain

8. Conclusions

Answer to research question: Yes

Best performance on domains:

- Robot: 100%
- ASCII Art: 24%
- String: 50%

Biggest limitations on performance:

- Max Iterations
- Time-out
- Lack of Loops