

## Introduction

- Storing trains is a complex problem
- TUSP: Train Unit Shunting Problem
- PDDL: Planning Domain Definition Language, used for scheduling
- Shunting yards have different layouts
- Apply and combine existing methods for real world replication

## Research Question

Can a planner in PDDL be optimised which handles domains that contain commonly encountered types of shunting yard layouts?



Figure 1a: example Shuffleboard



Figure 1b: example carousel



Figure 1c: example station

## Method

- **Creating the domain**
  - types
  - predicates
  - actions
- **Creating problem instances**
- **Evaluating planners**
  - Speed
  - Plan cost
  - Solvability
- **Optimising planners**
  - Improving the planner
  - Improving the domain



Figure 2: example carousel using PDDL

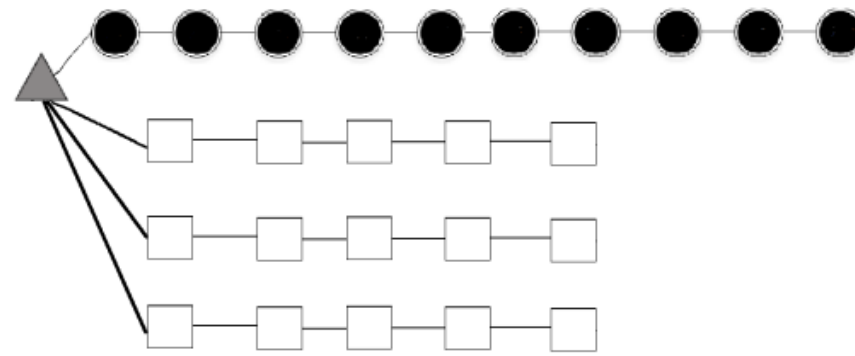


Figure 3: Complex Shuffleboard Problem

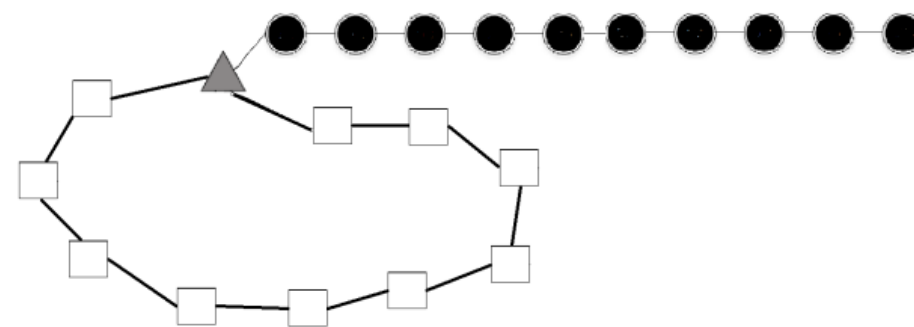


Figure 4: Complex Carousel Problem

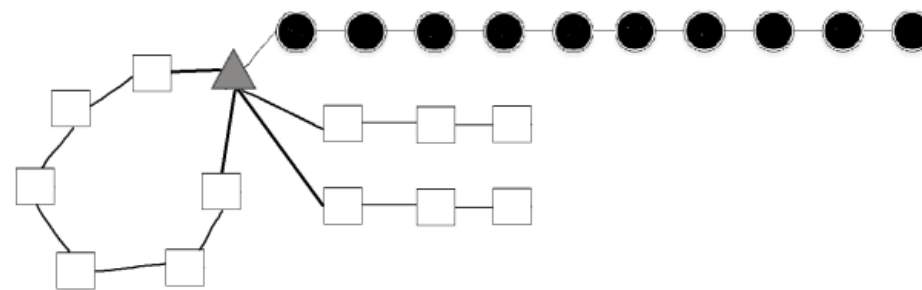


Figure 5: Complex Station Problem

	Shuffleboard	Carousel	Station
<b>Baseline</b>	1200s N/A cost False	1200s N/A cost False	1200s N/A cost False
<b>Team 2</b>	1200s N/A cost False	1200s N/A cost False	1200s 73 cost False
<b>Team 4</b>	182s 213 cost True	2.6s 199 cost True	3.2s 185 cost True
<b>Team 35</b>	336s N/A cost False	323s N/A cost False	296s 173 cost True

Table 1: Evaluation of different planners

## Results

- **Finalizing the domain**
  - Last In First Out tracks
  - Free tracks
  - Switching tracks
- **Optimisation of the planner**
  - SAT solver
  - LIFO tracks
  - Table 2
- **Complex problems**
  - Figures 3 - 5
- **Evaluating planners**
  - Table 1
  - Team4 best results

**predicates:**  
 (nextTo ?x ?y - trackpart)  
 (next ?x ?y - trackpart)  
 (prev ?x ?y - trackpart)  
 (last-track ?x - trackpart)



Figure 5: LIFO track optimisation

	Shuffleboard	Carousel	Station	Shuffle2
<b>Team4</b>	182s 213 cost True	2.6s 199 cost True	3.2s 185 cost True	47.5s 170 cost True
	Improved	Improved	Improved	Improved
<b>Team4</b>	6.4s 145 cost True	3s 193 cost True	10s 176 cost True	5.4s 151 cost True

Table 2: Evaluation of optimisation on the domain

## Conclusion

- **Different shunting yards**
  - LIFO vs. Free tracks
- **PDDL for TUSP**
  - Domain
  - Problems
- **Real-world integration**
- **Future work**
  - Explore other planners
  - More optimisations
  - Real problems
- **Contributions**
  - Domain
  - Evaluation
  - Optimisation