

Optimal Decision Trees for the Algorithm Selection Problem

Balancing Performance and Interpretability

1. Introduction

- The Algorithm Selection Problem (ASP) is a challenge in computer science aimed at predicting the most effective algorithm for a given instance of a computationally difficult problem. These problems occur frequently across various industries, such as finance, healthcare and energy [1].
- Tree-based models are a widely used machine learning model and have been used to solve the ASP [1]. While more complex tree-based models, like random forests, offer good performance, they're often not easily interpretable [2].
- The relation between the performance and interpretability is usually depicted in the literature as shown in figure 1, which shows interpretability as inversely proportional to performance, while this may not be true.
- Optimal decision trees aim to provide the best of both worlds by providing shallow trees which are optimal based on a specified objective function and tree depth. These optimal decision trees offer good performance on out of sample data [3].

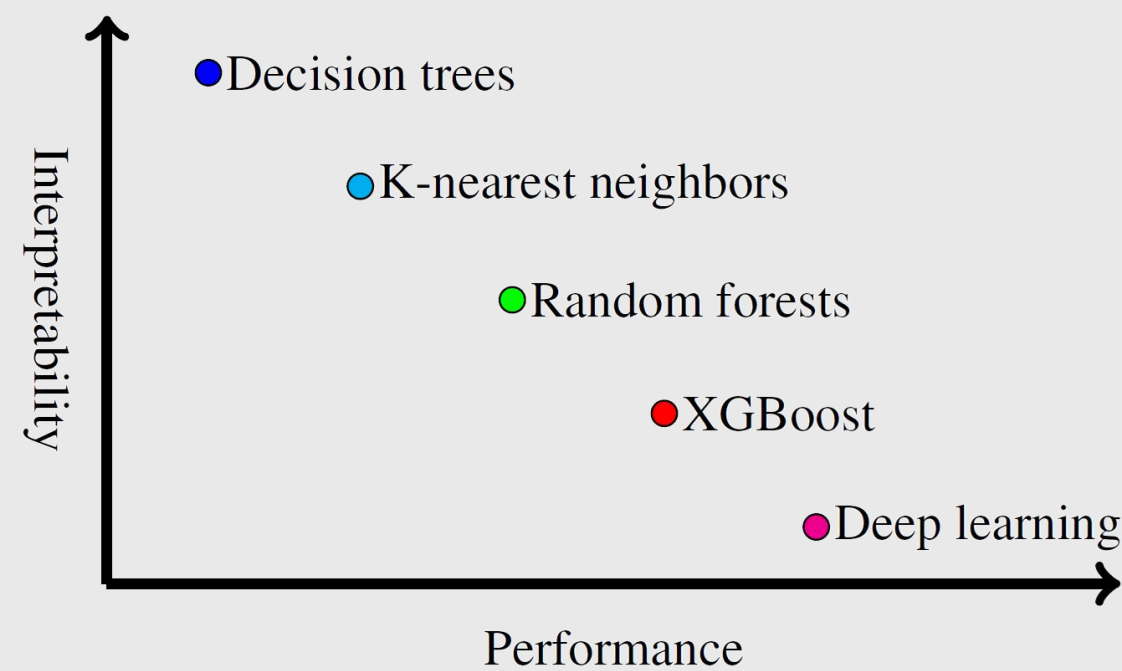
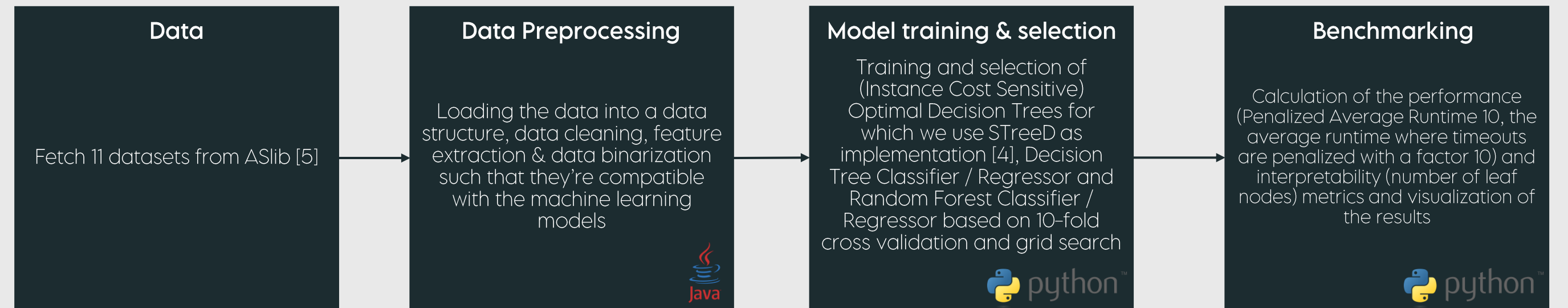


Figure 1: The interpretability – performance trade-off as presented by Sheykhoumousa and Mahdianpari [6]

2. Research question

What is the trade-off between performance and interpretability when solving the Algorithm Selection Problem (ASP) with optimal decision trees compared to other tree-based methods such as heuristic trees and random forests?

3. Methodology

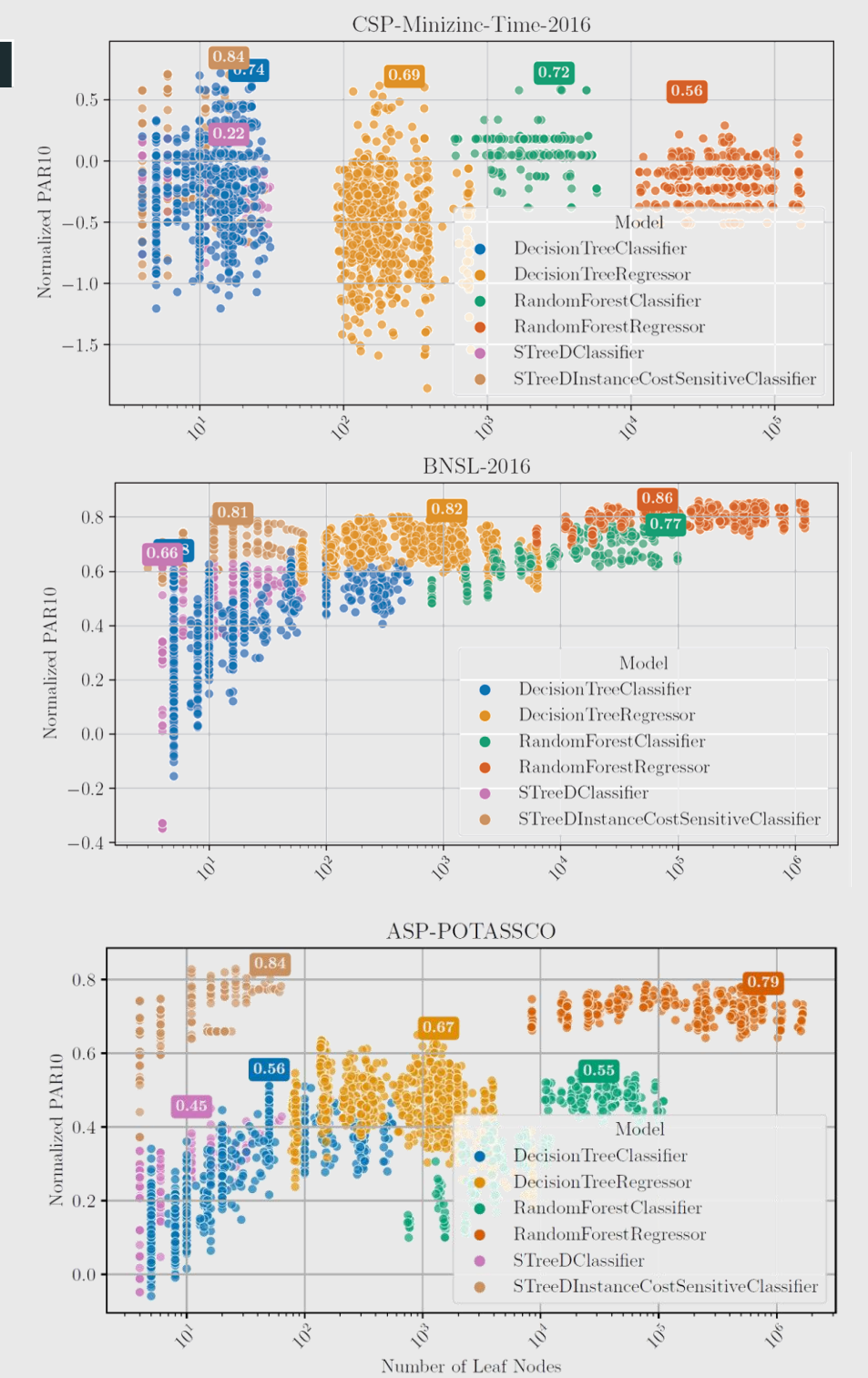


4. Experiments & Conclusions

	Mean Normalized PAR10*	Mean # Leaf Nodes	Std. deviation # Leaf Nodes
Decision Tree Classifier	0.49	111.00	123.62
Decision Tree Regressor	0.49	704.36	526.89
Random Forest Classifier	0.51	19168.00	22288.12
Random Forest Regressor	0.69	490705.09	510816.79
STreeD	0.27	14.18	9.85
STreeD Instance Cost Sensitive	0.70	19.64	13.46

Scenario	Decision Tree Classifier	Decision Tree Regressor	Random Forest Classifier	Random Forest Regressor	STreeD	STreeD Instance Cost Sensitive
ASP-POTASSCO	0.56	0.67	0.55	0.79	0.45	0.84*
BNSL-2016	0.68	0.82	0.77	0.86*	0.66	0.81
CSP-Minimize-Time-2016	0.74	0.69	0.58	0.56	0.22	0.84*
MAXSAT-WPMS-2016	0.58	0.60	0.56	0.83*	0.22	0.72
MAXSAT19-UCMS-ALGO	0.46	0.58	0.41	0.70*	0.41	0.59
MIP-2016	0.72	0.47	0.50	0.38	0.60	0.72*
PROTEUS-2014	-0.12	0.31	-0.11	0.59	-0.55	0.59*
QBF-2016	0.31	0.32	0.49	0.74*	-0.13	0.64
SAT11-HAND-ALGO	0.63	0.62	0.72	0.79*	0.60	0.74
SAT12-ALL	0.58	0.57	0.82	0.84*	0.49	0.77
SAT16-MAIN	0.23	0.25	0.13	0.39	-0.05	0.41*

Instance cost sensitive STreeD offers comparable or better performance and scales much better in terms of performance / interpretability, meaning there's no apparent interpretability - performance trade-off for Optimal Decision Trees for the ASP when compared to these tree-based models



*Normalized PAR10 is the normalized version of the Penalized Average Runtime 10 (PAR10), and is represented as a fraction of the best possible solver compared to the best solver on average, i.e. a 1 corresponds to a perfect score and a 0 corresponds to no increase in performance

References

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Author: Daniël Poolman
 Supervisors: Dr. Emir Demirović, Jacobus G.M. van der Linden
 Examiner: Dr. David M.J. Tax